

Hardware–Software Co-Design for Grouped-Query Attention on AHBM

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Executive Summary

Grouped-Query Attention (GQA) has largely replaced GPT-3-style multi-head attention in modern decoder-only LLMs (e.g., Llama 3 and Mistral) due to its reduced memory and bandwidth requirements. Mapping GQA efficiently onto AHBM introduces three architectural requirements: optimized placement of KV caches and weights to minimize inter-PE communication, low-overhead support for unavoidable cross-PE traffic, and efficient pipelining of memory accesses and computation within each PE.

To address these requirements, this report introduces three hardware–software co-design mechanisms: GQA-aware placement of KV caches and weights across TCM, SRAM, and HBM; PE_IPCQ, an efficient on-device collective communication primitive; and a composite-command GEMM pipeline that tightly pipelines memory and compute operations within each PE under PE_SCHEDULER control. Kernbench-based evaluation show up to 38 % lower collective communication overhead, 25 % to 35 % lower all-reduce latency than a mesh-based interconnect, and up to 78 % of peak MAC efficiency for compute-intensive GEMM kernels. These results demonstrate that the fused GQA kernel can efficiently exploit AHBM’s HBM bandwidth.

While GQA serves as the motivating workload in this study, the resulting architectural mechanisms are broadly applicable across the AHBM software stack. PE_IPCQ provides a scalable communication substrate for collective operations and communication-intensive workloads, while composite-command execution enables efficient fusion of memory movement, GEMM kernels, normalization, and other element-wise operations. Together with the hierarchical data-placement framework, these capabilities form a reusable foundation for future AI kernels and communication libraries on AHBM. Looking ahead, these same mechanisms provide the basis for optimizing FFN-intensive workloads such as Mixture-of-Experts (MoE) layers and for developing integrated optimization strategies spanning both attention and MoE components within next-generation AI models.

1 Introduction

AHBM integrates compute units directly into the HBM stack. Each processing element (PE) is paired with a dedicated slice of HBM and uses local TCM and SRAM to stage data between memory and the MAC array. On this memory-centric architecture, kernel performance depends not only on compute throughput but also on how effectively data is placed, moved, and shared across the memory hierarchy and between PEs. Optimizing AI kernels on AHBM therefore requires hardware–software co-design, in which kernel algorithms and architectural mechanisms are developed together.

To enable detailed performance analysis and rapid design exploration, we developed **KernBench**, a source-level discrete-event simulation platform for AHBM. KernBench implements the AHBM execution model, including memory-system latencies, the PE execution model, inter-PE communication, and host-side orchestration, while executing both kernel and host software directly from source code. This provides fine-grained visibility into execution behavior. It enables systematic evaluation of hardware–software co-design choices independently of higher-level software stacks such as compilers and runtimes. All results presented in this report are obtained using KernBench, which serves as the common evaluation platform for all mechanisms and kernels discussed in this study.

This report focuses on Grouped-Query Attention (GQA), one of the most performance- and bandwidth-critical components of LLM inference. Modern decoder-only models such as Llama 3 and Mistral have largely transitioned from GPT-3-style multi-head attention (MHA) to GQA, in which multiple query heads share a single KV head to reduce KV cache capacity and memory-bandwidth requirements. While GQA improves system efficiency at the model level, mapping it efficiently onto AHBM introduces three architectural requirements: optimized placement of KV caches and weights to minimize inter-PE communication, low-overhead support for unavoidable cross-PE traffic, and efficient pipelining of memory accesses and computation within each PE.

To address these requirements, this report introduces three hardware–software co-design mechanisms. First, GQA-aware data placement distributes KV caches and

weights across the TCM/SRAM/HBM hierarchy to reduce communication overhead and improve data locality. Second, PE_IPCQ provides an efficient on-device collective communication primitive for reductions and other communication-intensive operations. Third, a composite-command GEMM pipeline tightly pipelines memory movement and computation within each PE under PE_SCHEDULER control, reducing command overhead while keeping the MAC array efficiently utilized.

The compute enabler (the composite-command GEMM pipeline, §3) and the communication enabler (PE_IPCQ, §4) are first developed and evaluated independently. The fused GQA kernel (§5) then combines them with GQA-aware data placement to demonstrate an end-to-end attention implementation on AHBM. The correspondence is direct: attention’s $QK^\top$ and PV products are precisely the GEMMs that benefit from the composite-command pipeline, while its KV reductions are precisely the collective operations that benefit from PE_IPCQ. Together, these mechanisms enable the fused GQA kernel to efficiently exploit AHBM’s HBM bandwidth.

Although GQA serves as the motivating workload for this study, the resulting mechanisms are intended as reusable building blocks for a much broader class of AI kernels. PE_IPCQ can support collective communication across distributed and communication-intensive workloads, while composite-command execution can be applied to GEMM-based kernels, feed-forward networks (FFNs), normalization, and other fused operator pipelines. Together with the hierarchical data-placement framework, these mechanisms form a foundation for future AI kernels and communication libraries on AHBM. In the second half of 2026, this foundation will be extended to FFN- and MoE-dominated workloads and to end-to-end optimization of complete LLM execution.

The remainder of this report is organized as follows. Section 2 describes the KernBench platform and the AHBM configuration used throughout this study. Sections 3, 4, and 5 present the composite-command GEMM pipeline, PE_IPCQ collective communication, and the fused GQA kernel, respectively. Section 6 discusses the broader architectural implications of these results. Finally, Sections 7 and 8 summarize the key findings and outline future work on FFN, MoE, and full-model optimization.

2 The KernBench Platform

All results in this report are produced on *KernBench*, a system-level discrete-event simulator for LLM kernels running on AHBM. This section explains why the platform exists, the device and execution model it presents to a kernel writer, how its latency model turns that execution into a number, and the concrete hardware configuration used for every experiment that follows.

2.1 Why KernBench: source-level kernels without a software stack

In a production end-to-end (E2E) stack, kernel performance is entangled with every layer above the hardware: the compiler’s tiling and scheduling choices, the framework’s operator dispatch, the collective library, and the runtime. Good E2E numbers require *all* of those layers to be co-optimized, which makes it hard to answer a narrower but more fundamental question: *given the hardware, how fast can a well-written kernel be, and which hardware features actually make it faster?*

KernBench is built to answer exactly that question. Kernels are written and executed at the *source level*—as algorithmic descriptions in a small tile-oriented kernel API—with no dependency on a compiler or any other software-stack layer. The simulator takes the kernel and a hardware topology and reports the latency the modeled hardware would deliver. This isolation is deliberate: it lets us study algorithm-level optimizations (how to tile a GEMM, how to schedule a collective, how to fuse an attention kernel) and the hardware features that support them, without the confound of compiler maturity or framework overhead. The cost is that KernBench numbers are *not* E2E latencies; they are the achievable-kernel latencies an ideal software stack would expose.

2.2 Device and execution model

KernBench models AHBM as a hierarchy of SIPs, CUBEs, and processing elements (PEs). At the system level, multiple SIPs are connected through inter-package links, while each SIP contains a collection of CUBEs joined by an on-package interconnect (Fig. 1).

Each CUBE contains eight PEs, shared SRAM, HBM controllers, an M_CPU control processor, and an intra-CUBE router mesh (Fig. 2). Together these components form the execution substrate for all kernels evaluated in this report.

Within a PE, commands are dispatched by PE_CPU to PE_SCHED, which routes work to specialized execution engines—DMA, FETCH/STORE, GEMM, vector-math, and IPCQ (Fig. 3). Commands come in two flavours. *Atomic* commands target a single engine—a plain DMA read, a GEMM tile, a vector-math op, an IPCQ send/receive—and are the natural unit for short or special-purpose work; the PE_CPU itself also runs control-plane work directly. *Composite* commands, by contrast, carry an ordered pipeline of operations across multiple engines (DMA_READ → FETCH → GEMM/MATH → STORE → DMA_WRITE) that the PE_SCHED tiles and streams without per-tile redispach. The composite form is the substrate for the GEMM optimization (§3) and, combined with on-PE collectives, for fused attention (§5).

KernBench is layered along the flow of a request:

- The **runtime API** is host-facing and topology-agnostic—it deploys tensors and launches kernels but

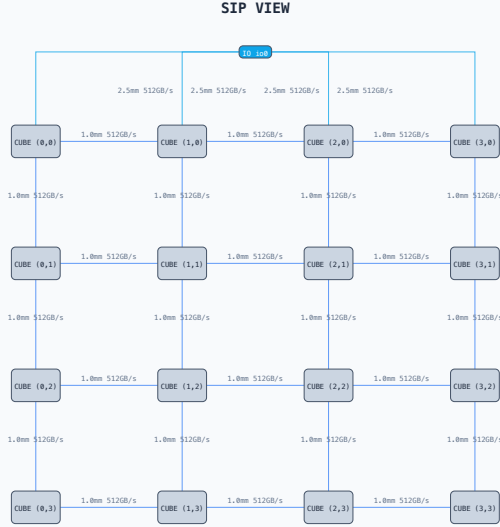


Figure 1: Modeled hardware graph at the *SIP* level (one example configuration; specific parameters in §2.4 / Table 1). The *SIP* holds a 4×4 mesh of CUBEs and an IO chiplet, with each line a directed link labelled by its physical distance and bandwidth.

knows nothing about routing or interconnect.

- The **simulation engine** schedules discrete events and routes every request through the modeled graph.
- The **components** are device-side nodes that model hardware behaviour: the per-PE blocks (scheduler, DMA, GEMM and vector-math engines, TCM, IPCQ), the NoC routers, the HBM controllers, and the inter-chiplet links.

Data and timing are handled in two passes, so that a kernel’s numeric results and its latency are computed consistently but independently.

2.3 Latency model: graph traversal and contention

The modeled hardware hierarchy described above is represented internally as a directed graph. Nodes correspond to hardware components—PEs, routers, memory controllers, SRAM blocks, IO chiplets—while edges represent communication links with associated bandwidth (GBs^{-1}) and propagation (ns) attributes. Every operation in KernBench—DMA transfers, remote memory accesses, collective communication, command dispatch—is modelled as a traversal through this graph. End-to-end latency is decomposed into four contributions accumulated along the traversal path (Fig. 4): **per-node overhead** at each component, **per-edge transmission** on each wire,

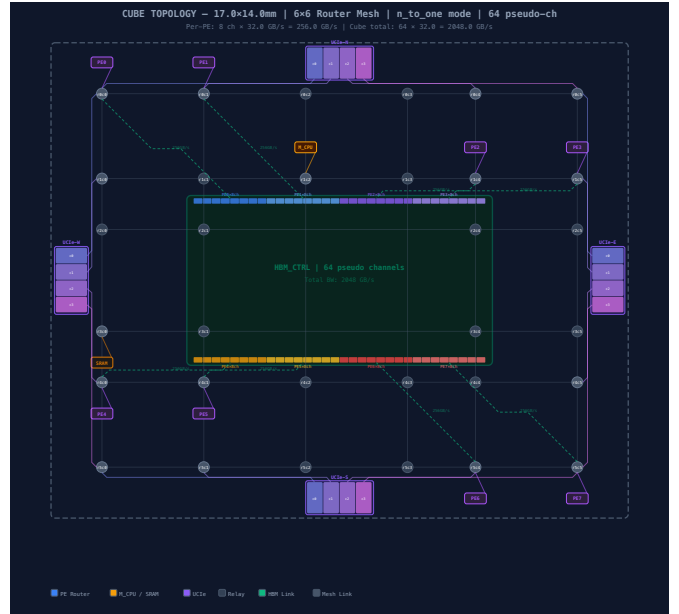


Figure 2: Modeled hardware graph at the *CUBE* level—a zoom-in on one CUBE node from Fig. 1. The CUBE holds 8 PEs (each with its own HBM channels), the *M_CPU* control processor, a shared SRAM, an intra-CUBE NoC router mesh, and UCIE links to neighbouring CUBEs.

drain (per-flit service occupancy) at the destination, and **queuing delay** at the shared FIFOs that the wire and the destination share between concurrent transactions.

The hardware as a graph. The topology is compiled once at configuration time into this graph and is never mutated during a run. There are no hidden shortcuts, implicit bypasses, or magic paths: if a request reaches its destination, the path it took is explicit in the graph, and the latency it incurred is the sum of the per-node and per-edge costs paid along that path. The same graph representation applies recursively at every hierarchy level—system, *SIP* (Fig. 1), *CUBE* (Fig. 2), and *PE* (Fig. 3).

From graph to discrete-event simulation. The graph is driven by a discrete-event engine. Two kinds of events advance simulation time: *node events* (component switching overhead, service completions such as an HBM channel commit or a GEMM tile finish) and *edge events* (the flit-by-flit serialization of a payload across a bandwidth-limited link). The engine maintains a priority queue of pending events ordered by their scheduled time and fires them one at a time, with ties broken under a deterministic policy so that the same kernel on the same topology always yields the same trace. Per-request correlation IDs are stamped at injection and carried through every hop, so the path from injection to completion is fully traceable. Every nanosecond in a reported latency corresponds to exactly one of these events on exactly one node or edge—there is no slack in the budget.

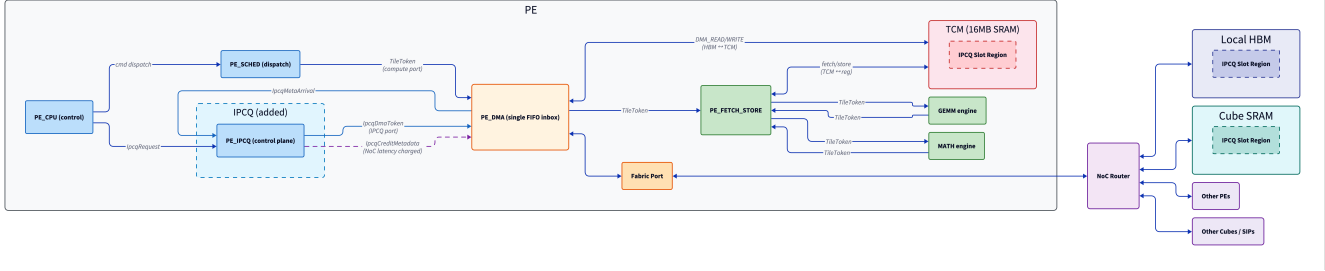


Figure 3: Modeled PE architecture used in this report—one example configuration whose specific parameters are listed in §2.4 (Table 1); KernBench is not tied to this particular decomposition and supports arbitrary PE block layouts provided each component is given a port and bandwidth model. PE_CPU dispatches commands to the PE_SCHED, which routes tile-token streams through the PE_DMA, PE_FETCH_STORE, and GEMM/MATH engines along on-chip links; the PE_IPCQ provides the control plane for on-device collective communication.

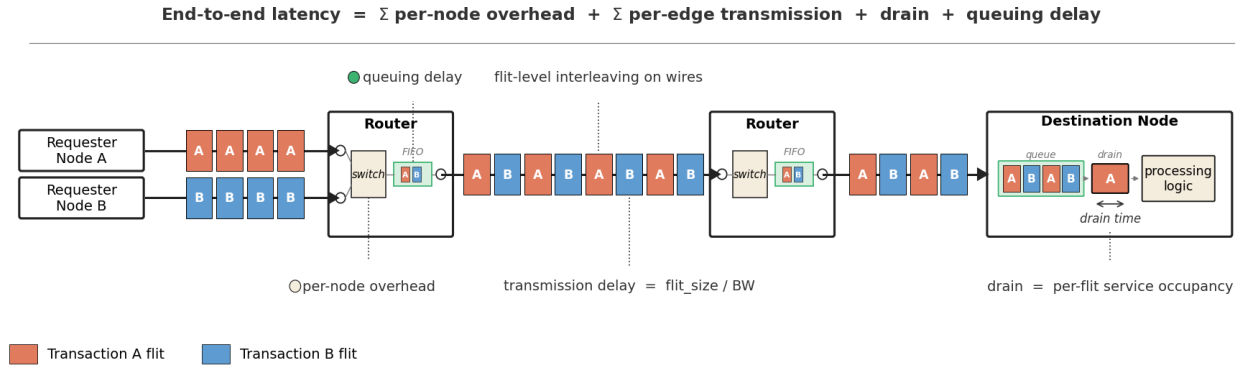


Figure 4: Conceptual schematic of the latency model. Two source nodes (Requester A/B) inject flits through a chain of routers into a destination node; on the shared edge between routers, flits from the two transactions are interleaved flit-by-flit by the wire’s FIFO arrival order. End-to-end latency is the sum of four contributions: **per-node overhead** (the switch’s fixed processing cost, shown in light yellow—the same colour as the destination’s processing-logic block), **per-edge transmission** ($\text{flit_size}/\text{BW}$ on each wire), **drain** (per-flit service occupancy at the destination’s channel), and **queuing delay** (waiting in a FIFO when a shared resource is busy). The places where queuing actually accumulates are highlighted in green: the router output queue and the destination’s input queue. This is the model, not a measurement; specific bandwidths and overheads are listed in §2.4 (Table 1).

Latency contributions. Three kinds of latency accumulate along a traversal: (i) *per-node fixed overhead*—each component carries a small switching cost (router decode, controller pickup, scheduler handoff); (ii) *per-edge transfer time*—each link’s payload is decomposed into fixed-size flits (default 256 B), and each flit arrives at $\text{prop} + \text{flit_bytes}/\text{bw}$ after the previous one, giving wormhole semantics across multi-hop paths; and (iii) *per-service occupancy*—memory controllers, GEMM stages, and collective engines hold the request for their service time before releasing it downstream. Each of these is attached to a specific node or edge in the graph; together they make up the entire latency budget.

Congestion: where bottlenecks emerge. The simulator’s sharpness comes from how it models contention for those nodes and edges. *Every directed edge has a FIFO*: an arriving flit takes its bandwidth-limited transfer time on top of whatever earlier flits are still being

served, so a busy link queues later traffic behind earlier traffic rather than transferring everything at peak BW. *HBM is modelled with per-pseudo-channel parallelism*: a stateless array of channel-availability timestamps with address-based channel selection captures the bank-level concurrency that real HBM exposes, so 64 channels per CUBE deliver real parallelism on uniform addresses but a hot channel surfaces as the bottleneck on skewed ones. *Every component has a serial worker*: a router carrying two heavy streams interleaves them at flit granularity in arrival order rather than fanning out for free, so two concurrent collectives sharing a link share its bandwidth, not double it. Without these mechanisms the simulator would simply re-confirm the peak-BW roofline; with them, it reveals where the real bottlenecks form and which hardware levers actually relieve them—which is exactly the question the codesign work in this report turns on.

Control-plane (issue) cost model. The cost of *issuing* a command is modelled structurally rather than with a per-operation calibration table. The PE control processor charges, per command,

$$d_{\text{cmd}} = \text{FIXED} + b_{\text{logical}} \cdot R,$$

where b_{logical} is the command’s hardware-logical byte size, **FIXED** captures the fixed per-command cost (queue-tail update, completion registration) and R captures the per-byte cost of serializing the command descriptor into the scheduler queue. The default anchoring (**FIXED** = 40 cycles, $R = 0.0625$ cycles/byte, i.e. 16 B cycle^{-1} , at 1 GHz) places a typical composite at roughly 43 ns, and a hard cap on a composite’s descriptor size prevents the model from rewarding arbitrarily large fused commands beyond what real descriptor queues accept. In the configurations measured here, command issue is not the bottleneck—data movement is—so this term stays small relative to DMA and collective time.

Accuracy. The model is precise about the effects that dominate kernel latency on this class of hardware: per-edge bandwidth occupancy and flit-level serialization, HBM pseudo-channel parallelism, and per-component switching overhead. Two independent cross-checks drawn from the experiments in this report confirm that this precision translates into physically reasonable kernel latencies. First, in the GEMM study (§3), simulator-measured MAC efficiency tracks an analytic ideal-pipeline model within roughly 10 % to 20 % across a wide range of tile counts; the residual gap is attributable to pipeline-fill and DMA effects the analytic model omits. Second, in the all-reduce study (§4, Fig. 7), simulator latency for a 2D-torus over six devices follows the expected startup-plus-per-packet shape across the entire payload sweep—tight at small payloads where startup dominates, and within a single-digit multiplicative factor at the largest payloads, where the residual gap is explained by per-router switching the analytic shape elides. A single-device point from an external full-system simulator (FSIM) at the largest payload sits an order of magnitude above the KernBench multi-device torus, illustrating the well-known gap between an achievable-kernel number and a full end-to-end-stack number rather than a model error. The known simplifications—FIFO router arbitration (instead of round-robin), HBM scheduler without write-buffer reordering, no bank conflict, no refresh or thermal effects, and no upstream backpressure—are the price of a deterministic, inspectable model. These simplifications bound the absolute accuracy, but the agreement with both analytic models and the external full-system simulator data above indicates that KernBench is sufficiently accurate for evaluating the *relative* hardware–software design trade-offs (tiling A vs. B, topology X vs. Y, with vs. without composite command, mesh vs. torus) that are the primary objective of this work.

Table 1: Modeled hardware configuration (shared by all experiments).

Parameter	Value
<i>Hierarchy</i>	
SIPs	2 (1D ring)
CUBEs per SIP	16 (4×4 mesh)
PEs per CUBE	8 (4 corners $\times$ 2)
PEs total	256
<i>Processing element (PE)</i>	
GEMM engine peak	8 TFLOP s^{-1} (f16)
TCM (on-PE)	16 MB, 512 GB s^{-1} R/W
kernel scratch	1 MB
DMA engines	1 read + 1 write
CPU / scheduler overhead	2 ns / 1 ns
<i>Memory (per CUBE)</i>	
HBM capacity	48 GB (8 slices)
HBM aggregate BW	1024 GB s^{-1}
HBM pseudo-channels	64 (8 per PE), 32 GB s^{-1} each
SRAM (shared)	32 MB, 128 GB s^{-1} link
HBM burst	256 B
<i>Interconnect</i>	
Intra-CUBE NoC link	256 GB s^{-1} , 2 ns/router
Inter-CUBE (UCIe PHY)	512 GB s^{-1} , 8 ns, XY routing
Inter-SIP (PCIe)	768 GB s^{-1} per endpoint
<i>Command-issue cost model (defaults)</i>	
FIXED per command	40 cycles
per-byte rate R	$0.0625 \text{ cycles/byte}$ (16 B cycle^{-1})
composite size cap	1024 B

2.4 Modeled hardware configuration

Table 1 summarizes the hardware configuration used for every experiment in this report. It is read directly from the simulator’s topology description; per-experiment workload parameters (matrix shapes, collective sizes, sequence lengths) are stated in their respective sections rather than here.

3 GEMM Acceleration via the Composite Command

3.1 Why it is needed

GEMM is the compute core of every transformer block—the QKV projections, the attention score and context products, and the feed-forward matrices are all matrix multiplications. On a tiled accelerator a single logical GEMM expands into many hardware tiles, and each tile must be read from HBM, fetched into the register file, computed, stored, and written back. If every one of those tile-stage steps were an independently issued command, two costs would dominate. First, the host and the PE control processor would pay a per-command issue overhead $O(\text{tiles} \times \text{stages})$ times, which for a deep- K reduction is hundreds to thousands of issues. Second,

with stages dispatched one-at-a-time the scheduler cannot overlap the DMA of the next tile with the compute of the current one—the pipeline never fills, and the MAC array sits idle waiting for data. The hardware question is therefore: what issue mechanism lets a single GEMM saturate the MAC array without drowning in command overhead?

3.2 Design

The answer is the *composite command*. A single command carries the ordered tile pipeline

DMA_READ → FETCH → GEMM → STORE → DMA_WRITE

and the PE scheduler splits the payload into hardware tiles (here $32 \times 64 \times 32$), emitting one tile token per tile. Subsequent stages are reached by *token self-routing* between the on-PE engines, so a tile flows DMA → fetch → GEMM → store without returning to the scheduler between stages. Because the whole pipeline is described by one command, the issue cost is paid once per GEMM rather than once per tile-stage, and the scheduler is free to keep every stage busy on different tiles simultaneously—tile i ’s GEMM overlaps tile $i+1$ ’s DMA read. A multi-operation composite additionally lets an epilogue (for example a vector-math step) ride the same tile loop, firing per K -tile, per output tile, or once per kernel according to its declared scope; this is what later allows an attention kernel to fuse its softmax work into the GEMM pipeline (§5).

3.3 Results

We sweep eight GEMM shapes spanning square, tall, wide, and deep- K geometries, under three operand-staging variants (*ref_ref*, both operands streamed from HBM; *load_ref*, one operand resident in TCM; *load_load*, both resident). Figure 5 reports MAC utilization and efficiency, and Figure 6 breaks the kernel into per-stage engine busy time.

Two regularities stand out. (i) Utilization is governed by how completely the problem fills the MAC tile: the three under-tile shapes are hard-capped well below 100%, independent of how the kernel is issued. (ii) Among tile-filling shapes, efficiency is governed by tile count—more tiles amortize the one-time pipeline fill and issue cost, so the deep- K shape reaches ~78% of peak while a single-tile shape reaches only ~23%. The stage breakdown explains why: with 48 tiles the GEMM and Fetch stages overlap and stay busy, whereas the low-reuse shape spends most of its time moving data in and out.

3.4 Analysis and meaning

The composite command does not manufacture bandwidth or MAC throughput; it removes the two software-shaped obstacles between a GEMM and its hardware

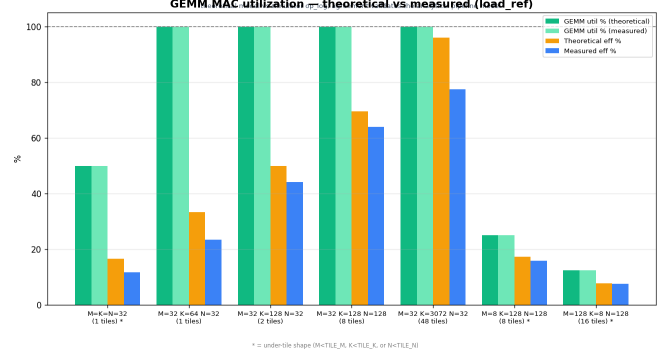


Figure 5: GEMM MAC utilization and efficiency, theoretical vs. measured. Tile-fill sets the ceiling: under-tile shapes (marked *) such as $M=K=N=32$, $M=8$, and $K=8$ cannot fill the MAC tile and cap at 50%, 25%, 12.5%. For tile-filling shapes, efficiency climbs with tile count—from ~23% at one tile to ~78% measured at 48 tiles ($K=3072$)—and the measured bars track the analytic prediction within 10% to 20%.

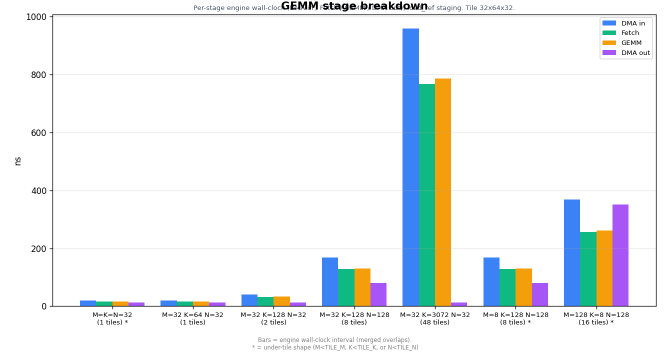


Figure 6: Per-stage engine wall-clock (DMA in, Fetch, GEMM, DMA out) under *load_ref* staging. For the deep- K shape ($K=3072$, 48 tiles) the Fetch and GEMM stages are large and comparable (~770 and 785ns) while DMA-out is negligible—a compute-rich, well-pipelined regime. For the low-reuse shape ($M=128$, $K=8$, $N=128$) DMA-out grows to ~350 ns and compute is small—a data-movement-bound regime.

roofline. By paying issue cost once per GEMM and chaining tile-stages through token self-routing, it lets the scheduler keep the pipeline full, so compute-rich shapes actually reach the efficiency their arithmetic intensity allows (~78% measured at 48 tiles), and data-bound shapes actually reach their DMA bound instead of stalling on command overhead. The close agreement between measured and theoretical efficiency (Figure 5) is also the report’s primary validation that KernBench’s latency model is faithful in the regime that matters. The hardware implication is concrete: a single-command, self-routing tile pipeline is the issue mechanism that makes the MAC array usable, and it is a prerequisite—not a luxury—for the fused attention kernel of §5.

4 PE_IPCQ and Collective Communication

4.1 Why it is needed

Distributing a transformer across devices turns every tensor-parallel layer into a collective: partial results computed on different PEs, CUBEs, and SIPs must be summed and redistributed with an all-reduce. If that collective is handled by the host or by a generic DMA path, three problems appear. The reduction traffic competes with the kernel’s own compute DMA on the same links, causing head-of-line blocking; there is no efficient peer-to-peer ring primitive, so data takes extra hops; and the ordering is hard to make deterministic. The hardware question is how to perform collectives *on the device*, overlapped with compute and reproducible run-to-run.

4.2 Design

KernBench models a dedicated per-PE collective engine, **PE_IPCQ** (inter-PE communication queue). It is a control-plane block: it owns the ring-buffer address arithmetic, head/tail pointers, peer-pointer caches, backpressure, and the four-direction (N/S/E/W) neighbor map, with eight ring buffers per PE (four directions $\times$ {tx, rx}). Crucially, PE_IPCQ does *not* move data itself—it delegates the actual transfer to PE_DMA, keeping a clean control/data split. To stop collective traffic from blocking compute, PE_DMA is extended into a two-channel virtual-channel model: **vc_compute** carries tile load/store for GEMM and vector math, **vc_comm** carries IPCQ sends, each with an independent state machine. The same physical link is shared but progresses in chunks (256 B), so a large GEMM DMA does not lock the link end-to-end against a pending reduction. On top of this substrate the collective runs a hierarchical local-reduce / global all-reduce-broadcast schedule across whatever inter-device topology the configuration specifies.

4.3 Results

Following the milestone-evaluation convention, the collective sweep builds its own six-device (six-SIP, 2×3) configurations—distinct from the two-SIP default of Table 1—and measures all-reduce latency as a function of payload size for three inter-device topologies: a 1D ring, a 2D mesh (no wrap), and a 2D torus. Table 2 and Figure 7 report the result.

Three findings follow. First, topology matters and the effect grows with size: at 96 kB/PE the 2D torus is 25 % faster than the mesh and 19 % faster than the ring, because its wrap-around links shorten the worst-case reduction path. Second, the measured curves grow smoothly with payload and stay within a small constant factor of the analytic torus model, with the gap reflecting real link serialization that the analytic model idealizes away.

Table 2: All-reduce latency (ns) across six devices, by topology and per-PE payload. Lower is better; the torus wins at every size.

Bytes/PE	2D mesh	Ring 1D	2D torus
256	2667	2365	1701
4,096	4450	4082	3038
16,384	8900	8217	6403
65,536	26705	24766	19865
98,304	38574	35798	28840

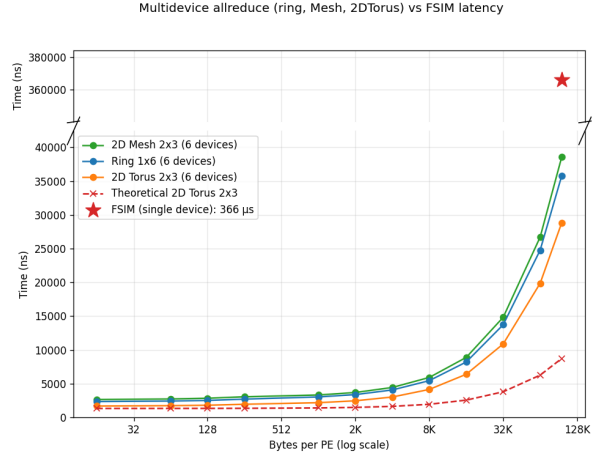


Figure 7: All-reduce latency vs. per-PE payload for the three topologies, against the analytic torus model and an external full-system simulator (FSIM) reference. The measured torus tracks the analytic curve within a small constant factor; the FSIM single-device point (366 μ s) sits an order of magnitude above the KernBench algorithmic latency, illustrating the difference between an achievable-kernel number and a full end-to-end-stack number.

Third, where the IPCQ staging buffer lives is a first-order knob: keeping it in on-PE TCM is materially faster than HBM or shared SRAM at large payloads (Figure 8).

4.4 Analysis and meaning

PE_IPCQ turns the collective from an off-device, contention-prone operation into an on-device primitive whose latency tracks the interconnect’s physical limits. The control/data split keeps the engine small while reusing PE_DMA for movement, and the virtual-channel split is what lets a reduction proceed without stalling the compute DMA that feeds the very GEMMs producing the partials—the same property the fused attention kernel relies on when it interleaves KV reduction with score computation (§5). For the hardware roadmap the results argue two things: provisioning wrap-around (torus) inter-device links is worth roughly a 20–25 % collective-latency reduction at scale, and giving the IPCQ a fast on-PE staging buffer (TCM) rather than forcing it through HBM or SRAM is worth another 14–38 % at large payloads.

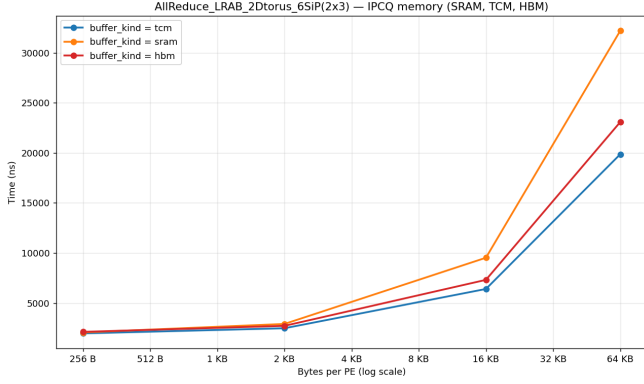


Figure 8: Effect of IPCQ staging-buffer placement (2D torus). At 64 KiB/PE, TCM staging (19 865 ns) beats HBM (23 081 ns) by ~14 % and SRAM (32 201 ns) by ~38 %; at small payloads the three are indistinguishable.

5 Fused Grouped-Query Attention

5.1 Why it is needed

Attention is the 1H focus, and it is where the two preceding optimizations have to come together. Grouped-Query Attention (GQA) shrinks the KV cache by sharing each KV head across a group of query heads (here $h_q = 8$ query heads to $h_{kv} = 1$ KV head, a group factor $G = 8$), which makes decoding feasible at long context but also makes it acutely memory-bound: a decode step processes a single query position ($T_q = 1$) against the entire KV history, so its arithmetic intensity is low and its time is dominated by streaming the KV cache out of HBM. FlashAttention-style tiling with an online-softmax merge avoids ever materializing the full score matrix, but realizing it as a fast *fused* kernel needs both building blocks from this report: efficient GEMM issue (§3) for the $Q \cdot K^\top$ and $P \cdot V$ products, and an efficient on-device reduction (§4) for the multi-user and sequence-parallel KV reductions. This section is the capstone: the fused kernel that uses the composite command and PE_IPCQ at the same time. Multi-head attention (MHA) was studied in prior work and serves here as the established baseline rather than being re-derived.

5.2 Design

The fused GQA kernel issues its matrix products as scheduler-managed composite commands and keeps the online-softmax merge and the cross-device KV reduction inside the kernel, on PE_IPCQ. Two kernel families cover the two phases. The *prefill* kernel is head-parallel and rotates the KV shards around an inter-CUBE ring (“Ring KV”). The *decode* kernel is head-replicated with a statically sharded KV cache and reduces partial attention outputs through an M-fold intra-CUBE chain and, for

Table 3: Fused GQA per-panel latency and operation mix. Compute (GEMM, MATH) is a tiny fraction of DMA occupancy; IPCQ copies grow with users and PEs.

Panel	Lat. (ns)	GEMM	IPCQ	DMA rd
prefill C=1	445	2	0	3
prefill C=4 (Ring)	4630	32	24	12
decode C=1, P=8	3632	16	21	24
decode C=4, P=8	6693	64	93	96

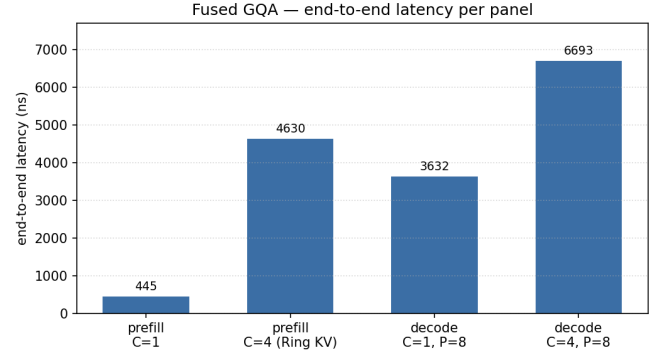


Figure 9: Fused GQA end-to-end latency. Latency grows from 445 ns (single-user prefill) to 6693 ns (four-user decode) as the KV history and the number of participating devices grow.

multiple users, a two-level reduce-to-root. Two further primitives make long context practical: a *lazy load* that issues the KV DMA_READ and returns immediately, auto-waiting only at first use so that KV load overlaps score computation; and per-tile *scratch recycling* that keeps the running softmax accumulators (m, ℓ, O) in a persistent arena while freeing per-tile temporaries, so the kernel fits the 1 MiB scratch budget across many tiles. A further refinement that restructures the decode step into two stateful composites (a named *softmax_merge* recipe) is designed but not yet wired into the measured path; results below reflect the implemented kernel only.

5.3 Results

We measure four headline panels that vary the user count C and the phase: single- and multi-user prefill ($T_q = 4$, $S_{kv} = 16$), and single- and multi-user decode ($P = 8$ PEs, $S_{kv} = 64$ and 128), all at $d_{\text{head}} = 64$ and $G = 8$. For each panel we harvest end-to-end latency (max event end minus min event start, the same window convention as the GEMM study) together with the per-engine busy time and the operation mix. Figure 9 and Figure 10 report the result; the underlying numbers are in Table 3.

The dominant observation is in Figure 10: the compute engines are almost idle. The GEMM engine accumulates only 2 ns to 33 ns of busy time across the panels and the vector-math engine 5 ns to 688 ns, while the DMA engine accumulates 72 ns to 15 920 ns. Fused GQA, as modeled

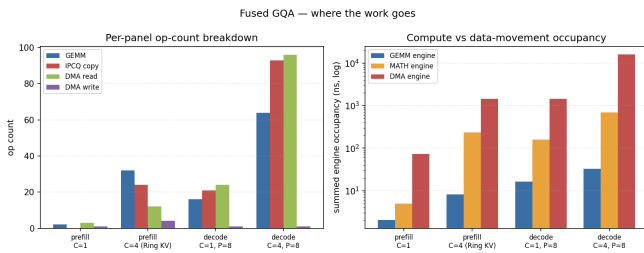


Figure 10: Where the work goes. Left: operation counts—GEMM and IPCQ-copy volume both scale with users and PEs. Right: summed engine occupancy on a log scale—the DMA engine dominates by two to three orders of magnitude over the GEMM and MATH engines in every panel.

here, is overwhelmingly data-movement bound. The operation mix shows why the collective machinery matters: IPCQ-copy count rises from zero (single-user prefill) to 93 (four-user decode) as the kernel reduces partial outputs across more PEs and CUBEs, and DMA-read count rises in step as more KV shards are streamed. The PE control-processor dispatch cost registered as zero in this configuration—command issue is simply not on the critical path when data movement is this dominant.

5.4 Analysis and meaning

These panels are the clearest statement of the code-sign thesis in the report. Because the composite command keeps GEMM issue cheap and the MAC array barely occupied, the fused attention kernel’s latency is set almost entirely by data movement: streaming the KV cache and reducing partials across devices. That is precisely the cost that the communication-side work targets—PE_IPCQ for the on-device reduction, the lazy load for load/compute overlap, fast TCM staging and torus links for the reduction itself. In other words, the two enablers are not independent features that happen to appear in the same kernel; the GEMM optimization is what *exposes* the data-movement bottleneck (by removing the compute and issue overhead that would otherwise hide it), and the communication optimization is what *attacks* it. For an attention-dominated decoder the meaningful hardware investments are therefore the ones that move data faster and reduce it on-device—not additional MAC throughput, which this workload cannot use.

6 Discussion: which hardware changes are meaningful

Read together, the three studies point to a consistent ranking of where hardware investment pays off for attention-centric decoding.

The composite command is foundational, but indirectly. Its direct effect—driving compute-rich GEMMs

to ~78 % of peak—matters most for the compute-bound parts of a model (the large feed-forward and projection matrices). For attention itself, its more important effect is *diagnostic*: by making issue and compute nearly free, it removes the overhead that would otherwise mask the true bottleneck, and the fused GQA results then show unambiguously that the kernel is data-movement bound. Without a cheap, self-routing issue mechanism we would not be able to tell whether attention is slow because of compute or because of data movement; with it, the answer is clear.

The communication path is where attention latency actually lives. Every all-reduce and fused-GQA measurement says the same thing: the limiting resource is moving and reducing data, not multiplying it. That makes the PE_IPCQ design and the choices around it the highest-value hardware levers for this workload:

- **On-device collectives with a compute/communication virtual-channel split.** Performing the reduction on the device, with `vc_comm` separated from `vc_compute` so the reduction does not stall the compute DMA, is what lets attention overlap KV movement with score computation at all.
- **Fast on-PE staging memory.** Keeping the IPCQ buffer in TCM rather than HBM or SRAM is worth 14–38 % of collective latency at large payloads—a pure placement decision with a first-order effect.
- **Wrap-around (torus) inter-device links.** A torus fabric buys 20–25 % over a mesh or ring at scale by shortening the worst-case reduction path.

Raw MAC throughput is not the constraint for attention. The GQA panels leave the GEMM and vector-math engines two to three orders of magnitude below the DMA engine in busy time. Adding MAC area would not move decode latency; the workload cannot use it. This is the single most actionable finding for an attention-dominated roadmap.

Caveats. These conclusions are achievable-kernel results from a deterministic model, not E2E measurements; absolute numbers carry the model’s idealizations (§2.3), though the relative rankings that drive the recommendations are robust to them. The headline GQA panels are also at modest scale (up to four users, single SIP), and one designed refinement—the two-composite `softmax_merge` decode—is not yet in the measured path. Larger-scale and multi-SIP headline runs are 2H work.

7 Conclusion

This 1H work set out to make attention-centric LLM kernels fast through hardware–software codesign, and to

do so on a platform that isolates algorithm-level behavior from the rest of the software stack. The result is a coherent picture rather than three separate optimizations. A composite command that issues a tiled GEMM as one self-routing pipeline makes the MAC array usable—reaching ~78% of peak on compute-rich shapes with measured efficiency tracking theory—and, just as importantly, makes compute cheap enough that the real bottleneck becomes visible. A per-PE on-device collective engine, PE_IPCQ, turns all-reduce into a primitive whose latency follows the interconnect’s physical limits, with topology and staging-memory choices each worth tens of percent. Fused Grouped-Query Attention then combines the two and shows the payoff and the lesson at once: the kernel is data-movement bound, so the optimizations that move and reduce data—not those that add arithmetic—are what determine its speed.

The practical conclusion for the hardware roadmap is therefore specific. The changes worth keeping are the single-command self-routing GEMM pipeline, the on-device PE_IPCQ collective with its compute/communication virtual-channel split, fast on-PE staging memory, and wrap-around inter-device links. Additional MAC throughput is not, for this workload, a meaningful investment. KernBench made these conclusions measurable by holding everything except the algorithm and the hardware fixed; the next half extends the same method beyond attention to the rest of the decoder.

8 Future Work — 2H

The 1H work covered attention end to end. The natural next step is to complete the decoder and then to ask how compute and data should be distributed for realistic, agentic workloads.

From attention to the full decoder: FFN and MoE. A decoder block is attention followed by a feed-forward network (FFN), and in modern models that FFN is increasingly a mixture-of-experts (MoE) layer. The FFN is the compute-rich counterpart to attention—it is where the composite command’s MAC-efficiency gains (§3) should matter most—so adding it gives a balanced view of a full block instead of its memory-bound half alone. MoE adds a new dimension: a routing step selects a few experts per token, turning the dense FFN GEMM into a sparse, data-dependent dispatch. The open questions are how to issue expert GEMMs as composites under data-dependent token counts, and how to move tokens to experts efficiently—an all-to-all-shaped communication pattern distinct from the all-reduce studied here, and a natural extension of the PE_IPCQ work.

Compute and data distribution for full LLM decoding. With both attention and FFN/MoE in hand, the question becomes where each layer’s compute and

state should live. Attention is KV-bound and favors keeping the KV cache close to the PEs that consume it; FFN/MoE is compute-bound and favors spreading GEMM work across PEs; MoE routing makes the optimal placement token- and time-dependent. A 2H goal is to use KernBench to explore these placement and parallelization trade-offs—tensor vs. expert vs. sequence parallelism—under a single, software-stack-independent model, so the interconnect and memory implications of each choice are measured rather than assumed.

Agentic workloads. Agentic inference interleaves many short, bursty decode requests with tool use and long shared contexts, which stresses the system differently from a single long generation: context reuse across requests, dynamic batching, and uneven expert load all change how compute and data should be dispersed. Characterizing how total compute and data movement distribute across the SIP/CUBE/PE hierarchy under such workloads—and which of the 1H hardware levers still dominate when the workload is this irregular—is the broader 2H agenda.